

## Lecture 4

Binary search (cont.),
insertion/selection sort, analysis of quick sort

CS 161 Design and Analysis of Algorithms Ioannis Panageas

## Binary Search: Searching in a sorted array

- Input is a sorted array $A$ and an item $x$.
- Problem is to locate $x$ in the array.
- We will show that binary search is an optimal algorithm for solving this problem.


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```
def binarySearch(A,x,first,last)
if first > last:
    return (-1)
else:
    mid = \(first+last)/2\rfloor
    if x == A[mid]:
        return mid
    else if x < A[mid]:
        return binarySearch(A,x,first,mid-1)
    else:
        return binarySearch(A,x,mid+1,last)
binarySearch(A,x,0,n-1)
```


## Binary Search: Analysis of Running Time (continued)

- Binary search in an array of size 1: 1 decision
- Binary search in an array of size $n>1$ : after 1 decision, either we are done, or the problem is reduced to binary search in a subarray with a worst-case size of $\lfloor n / 2\rfloor$
- So the worst-case time to do binary search on an array of size $n$ is $T(n)$, where $T(n)$ satisfies the equation

$$
T(n)= \begin{cases}1 & \text { if } n=1 \\ 1+T\left(\left\lfloor\frac{n}{2}\right\rfloor\right) & \text { otherwise }\end{cases}
$$

- The solution to this equation is:

$$
T(n)=\lfloor\lg n\rfloor+1
$$

This can be proved by induction.

- So binary search does $\lfloor\lg n\rfloor+1$ 3-way comparisons on an array of size $n$, in the worst case.


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- It says: for every algorithm for finding an item in an array of size $n$, there is some input that forces it to perform $\lfloor\lg n\rfloor+1$ comparisons.
- It does not say: for every algorithm for finding an item in an array of size $n$, every input forces it to perform $\lfloor\lg n\rfloor+1$ comparisons.


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Hence any algorithm for locating an item in an array of size $n$ using only comparisons must perform at least $\lfloor\lg n\rfloor+1$ comparisons in the worst case.
So binary search is optimal with respect to worst-case performance.

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We will discuss in the class

- Comparison-based sorting algorithms (Insertion sort, Selection Sort, Quicksort, Mergesort, Heapsort)
- Bucket-based sorting methods


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- Consistent with philosophy of counting basic operations, discussed earlier.
- Misleading if other operations dominate (e.g., if we sort by moving items around without comparing them)
- Comparison-based sorting has lower bound of $\Omega(n \log n)$ comparisons. (We will prove this.)
$\Theta(n \log n)$ work vs. quadratic $\left(\Theta\left(n^{2}\right)\right)$ work



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Example: The list

$$
\begin{array}{llllll}
18 & 29 & 12 & 15 & 32 & 10
\end{array}
$$

has 9 inversions:

$$
\begin{array}{r}
\{(18,12),(18,15),(18,10),(29,12),(29,15), \\
(29,10),(12,10),(15,10),(32,10)\}
\end{array}
$$

## Insertion sort

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0

$k$


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- Work from left to right across array

$k$



## Insertion sort

- Work from left to right across array
- Insert each item in correct position with respect to (sorted) elements to its left

k



## Insertion sort pseudocode


def insertionSort(n, A):
for $k=1$ to $n-1$ :

$$
\mathrm{x}=\mathrm{A}[\mathrm{k}]
$$

$$
j=k-1
$$

$$
\text { while }(j>=0) \text { and }(A[j]>x):
$$

$$
A[j+1]=A[j]
$$

$$
j=j-1
$$

$$
A[j+1]=x
$$

## Insertion sort example

| 23 | 19 | 42 | 17 | 85 | 38 |
| :--- | :--- | :--- | :--- | :--- | :--- |


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- Storage: in place: $O(1)$ extra storage


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- Rearrange keys so small keys precede all large keys.
- Recursively sort small keys, recursively sort large keys.



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- Small keys are the keys $<x$.
- Large keys are the keys $\geq x$.



## Pseudocode for Quicksort

```
def quickSort(A,first,last):
    if first < last:
            splitpoint = split(A,first,last)
            quickSort(A,first,splitpoint-1)
            quickSort(A,splitpoint+1,last)
```



## The split step

```
def split(A,first,last):
    splitpoint = first
    x = A[first]
    for k = first+1 to last do:
        if A[k] < x:
            A[splitpoint+1] ↔ A[k]
            splitpoint = splitpoint + 1
    A[first] \leftrightarrow A[splitpoint]
    return splitpoint
```

Loop invariants:

- A[first+1..splitpoint] contains keys $<x$.
- A[splitpoint+1..k-1] contains keys $\geq x$.
- A[k..last] contains unprocessed keys.


## The split step

At start:


In middle:


At end:


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## Example of split step



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We can visualize the lists sorted by quicksort as a binary tree.

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- Identify each list with its split value.



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- Answer: The bound is tight. It is $\Theta\left(n^{2}\right)$. We will see why on the next slide.


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$\binom{n}{2}$ comparisons required. So the worst-case running time for Quicksort is $\Theta\left(n^{2}\right)$. But what about the average case ...?

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1. Use the binary tree of sorted lists
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4. Use this to compute the expected number of comparisons performed by Quicksort.

## Average-case analysis of Quicksort:



Sorted order: $\quad$| 15 | 18 | 22 | 23 | 27 | 36 | 79 | 83 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

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Examples:

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- 23 and 22 (both statements true)


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Examples:

- 23 and 22 (both statements true)
- 36 and 83 (both statements false)


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$=\frac{2}{j-i+1}$

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Define indicator random variables $\left\{X_{i, j}: 1 \leq i<j \leq n\right\}$

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X_{i, j}= \begin{cases}1 & \text { if keys } S_{i} \text { and } S_{j} \text { get compared } \\ 0 & \text { if keys } S_{i} \text { and } S_{j} \text { do not get compared }\end{cases}
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3. The expected value of $X_{i, j}$ is:

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E\left(X_{i, j}\right)=P_{i, j}=\frac{2}{j-i+1}
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So the average time for Quicksort is $O(n \lg n)$.

